

Closed-Form Matting

CVFX @ NTHU

30 April 2015

The Paper

- › *A Closed Form Solution to Natural Image Matting*
 - › Levin, Lischinski, and Weiss
 - › CVPR 2006

Compositing Equation

$$I_i = \alpha_i F_i + (1 - \alpha_i) B_i$$

composite foreground background

alpha channel

natural matting:

α_i , F_i , and B_i are unknowns

for a 3 channel color image

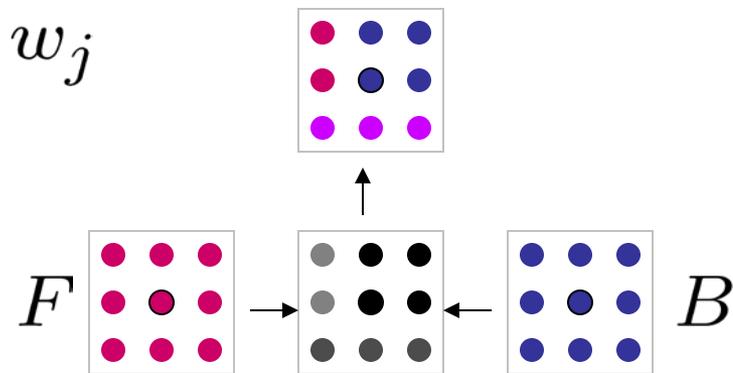
at each pixel there are 3 equations and 7 unknowns

Alpha Matting of Grayscale Images

- › **Assumption:** both F and B are approximately constant over a small window around each pixel
 - › Locally smooth \rightarrow linear relation

$$\alpha_i \approx aI_i + b, \quad \forall i \in w \leftarrow \text{a small window}$$

$$a = \frac{1}{F-B} \quad b = -\frac{B}{F-B}$$



$$\begin{aligned} I_i &\approx \alpha_i F + (1 - \alpha_i) B \\ I_i &\approx \alpha_i (F - B) + B \\ \alpha_i &\approx \frac{1}{F - B} I_i - \frac{B}{F - B} \end{aligned}$$



Optimization

- › Minimize the cost function

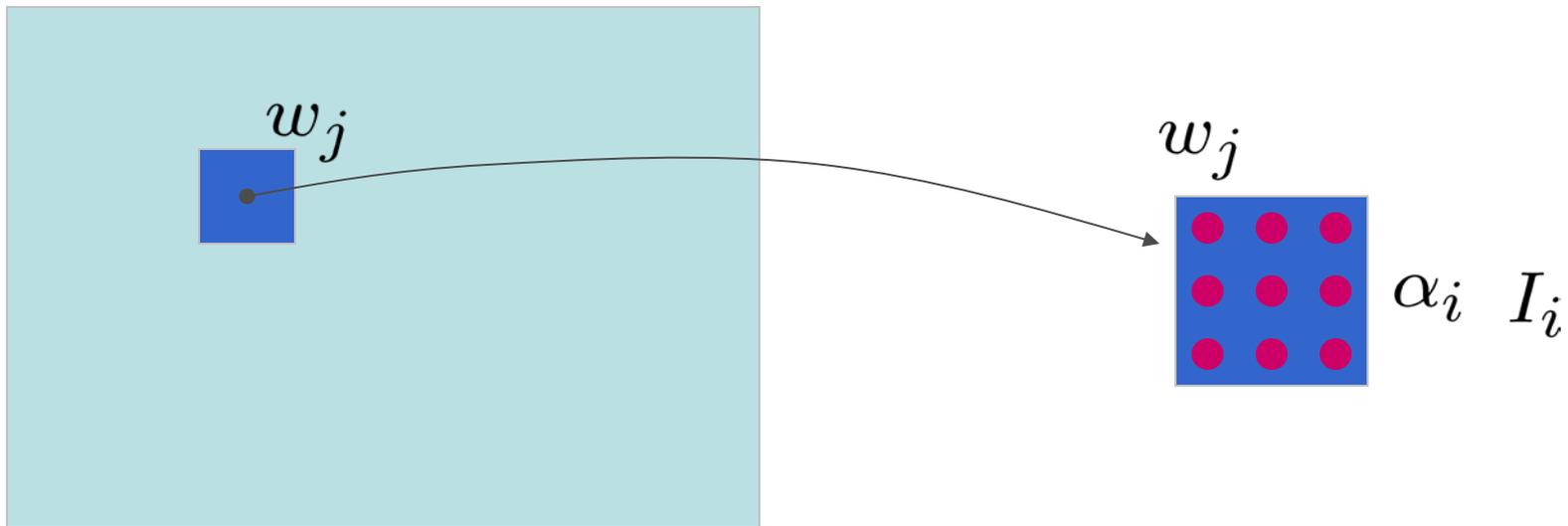
$$J(\alpha, a, b) = \sum_{j \in I} \left(\sum_{i \in w_j} (\alpha_i - a_j I_i - b_j)^2 + \epsilon a_j^2 \right)$$

where w_j is a small window around pixel j

a regularization term on a :

minimizing the norm of a biases the solution towards smoother α mattes $\alpha_i \approx \cancel{a} I_i + b, \quad \forall i \in w$

$a \ll 0$ implies that F and B are very different



$$J(\alpha, a, b) = \sum_{j \in I} \left(\sum_{i \in w_j} (\alpha_i - a_j I_i - b_j)^2 + \epsilon a_j^2 \right)$$

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$$J(\alpha, a, b) = \sum_k \left\| \begin{pmatrix} I_1 & \mathbf{1} \\ \vdots & \vdots \\ I_{|w_k|} & \mathbf{1} \\ \sqrt{\epsilon} & 0 \end{pmatrix} \begin{pmatrix} a_k \\ b_k \end{pmatrix} - \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_{|w_k|} \\ 0 \end{pmatrix} \right\|^2$$

$$J(\alpha, a, b) = \sum_k \left\| G_k \begin{bmatrix} a_k \\ b_k \end{bmatrix} - \bar{\alpha}_k \right\|^2$$



- › For a given alpha matte the optimal pair a_k^*, b_k^* inside each window w_k is the solution to the least squares problem

$$\begin{aligned}(a_k^*, b_k^*) &= \operatorname{argmin} \left\| G_k \begin{bmatrix} a_k \\ b_k \end{bmatrix} - \bar{\alpha}_k \right\|^2 \\ &= (G_k^T G_k)^{-1} G_k^T \bar{\alpha}_k\end{aligned}$$

Substituting

 a_k^*, b_k^*

$$\begin{pmatrix} a_k^* \\ b_k^* \end{pmatrix} = (G_k^T G_k)^{-1} G_k^T \bar{\alpha}_k$$

$$J(\alpha, a^*, b^*) = \sum_k \left\| G_k \begin{pmatrix} a_k^* \\ b_k^* \end{pmatrix} - \bar{\alpha}_k \right\|^2$$



$$\begin{aligned} J(\alpha) &= \sum_k \left\| \left(G_k (G_k^T G_k)^{-1} G_k^T - \mathbf{I} \right) \bar{\alpha}_k \right\|^2 \\ &= \sum_k \bar{\alpha}_k^T \bar{G}_k^T \bar{G}_k \bar{\alpha}_k \end{aligned}$$

$$\bar{G}_k = \mathbf{I} - G_k (G_k^T G_k)^{-1} G_k^T$$

$$\begin{aligned}\bar{G}_k^T \bar{G}_k &= (\mathbf{I} - G_k (G_k^T G_k)^{-1} G_k^T)^T (\mathbf{I} - G_k (G_k^T G_k)^{-1} G_k^T) \\ &= \mathbf{I} - G_k (G_k^T G_k)^{-1} G_k^T\end{aligned}$$

$$G_k = \begin{pmatrix} I_1 & 1 \\ \vdots & \vdots \\ I_{|w_k|} & 1 \\ \sqrt{\epsilon} & 0 \end{pmatrix}$$

the (i, j) -th element of $\mathbf{I} - G_k (G_k^T G_k)^{-1} G_k^T$ is

$$\delta_{ij} - \frac{1}{|w_k|} \left(1 + \frac{1}{\frac{\epsilon}{|w_k|} + \sigma_k^2} (I_i - \mu_k)(I_j - \mu_k) \right)$$

The (i, j) element

$$\begin{aligned} & \left(\mathbf{I} - G_k (G_k^T G_k)^{-1} G_k^T \right)_{ij} \\ &= \delta_{ij} - (I_i \ \mathbf{1}) \begin{pmatrix} \sum_n^{|w_k|} I_n^2 + \epsilon & \sum_n^{|w_k|} I_n \\ \sum_n^{|w_k|} I_n & |w_k| \end{pmatrix}^{-1} \begin{pmatrix} I_j \\ \mathbf{1} \end{pmatrix} \end{aligned}$$

$$\mathbf{I} = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & \dots & \\ & & & 1 \end{pmatrix}$$

$$\begin{pmatrix} I_1 & 1 \\ I_2 & 1 \\ \vdots & \\ I_{|w_k|} & 1 \\ \sqrt{\epsilon} & 0 \end{pmatrix} \left\{ \begin{pmatrix} I_1 & I_2 & \dots & I_{|w_k|} & \sqrt{\epsilon} \\ 1 & 1 & & 1 & 0 \end{pmatrix} \begin{pmatrix} I_1 & 1 \\ I_2 & 1 \\ \vdots & \\ I_{|w_k|} & 1 \\ \sqrt{\epsilon} & 0 \end{pmatrix} \right\}^{-1} \begin{pmatrix} I_1 & I_2 & \dots & I_{|w_k|} & \sqrt{\epsilon} \\ 1 & 1 & & 1 & 0 \end{pmatrix}$$

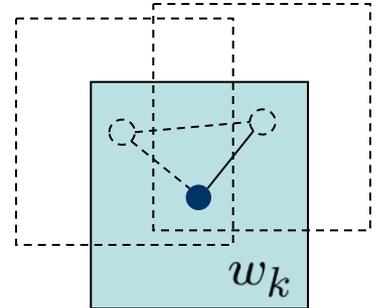
Compute the Inverse

$$\begin{aligned}
 & \left(\begin{array}{cc} \sum_n |w_k| I_n^2 + \epsilon & \sum_n |w_k| I_n \\ \sum_n |w_k| I_n & |w_k| \end{array} \right)^{-1} \\
 &= \frac{\left(\begin{array}{cc} |w_k| & -\sum_n |w_k| I_n \\ -\sum_n |w_k| I_n & \sum_n |w_k| I_n^2 + \epsilon \end{array} \right)}{|w_k| \sum_n |w_k| I_n^2 + \epsilon |w_k| - (\sum_n |w_k| I_n)^2} \\
 &= \frac{|w_k| \left(\begin{array}{cc} 1 & -\mu_k \\ -\mu_k & \sum_n |w_k| I_n^2 / |w_k| + \epsilon / |w_k| \end{array} \right)}{|w_k|^2 \sigma_k^2 + \epsilon |w_k|} \\
 &= \frac{1}{|w_k| \sigma_k^2 + \epsilon} \left(\begin{array}{cc} 1 & -\mu_k \\ -\mu_k & \sum_l |w_k| I_n^2 / |w_k| + \epsilon / |w_k| \end{array} \right)
 \end{aligned}$$

The (i, j) element

$$\begin{aligned}
& \left(\mathbf{I} - G_k (G_k^T G_k)^{-1} G_k^T \right)_{ij} \\
&= \delta_{ij} - (I_i \ 1) \begin{pmatrix} \sum_n^{|w_k|} I_n^2 + \epsilon & \sum_n^{|w_k|} I_n \\ \sum_n^{|w_k|} I_n & |w_k| \end{pmatrix}^{-1} \begin{pmatrix} I_j \\ 1 \end{pmatrix} \\
&= \delta_{ij} - (I_i \ 1) \frac{1}{|w_k| \sigma_k^2 + \epsilon} \begin{pmatrix} 1 & -\mu_k \\ -\mu_k & \sum_n^{|w_k|} I_n^2 / |w_k| + \epsilon / |w_k| \end{pmatrix} \begin{pmatrix} I_j \\ 1 \end{pmatrix} \\
&= \delta_{ij} - \frac{1}{|w_k| \sigma_k^2 + \epsilon} \left(I_i I_j - I_i \mu_k - I_j \mu_k + \frac{\sum_n^{|w_k|} I_n^2 + \epsilon}{|w_k|} \right) \\
&= \delta_{ij} - \frac{1}{|w_k| \sigma_k^2 + \epsilon} \left(I_i I_j - I_i \mu_k - I_j \mu_k + \mu_k^2 + \frac{\sum_n^{|w_k|} I_n^2}{|w_k|} - \mu_k^2 + \frac{\epsilon}{|w_k|} \right) \\
&= \delta_{ij} - \frac{1}{|w_k| \sigma_k^2 + \epsilon} \left((I_i - \mu_k)(I_j - \mu_k) + \sigma_k^2 + \frac{\epsilon}{|w_k|} \right) \\
&= \delta_{ij} - \frac{1}{|w_k|} \left(1 + \frac{1}{\sigma_k^2 + \epsilon / |w_k|} (I_i - \mu_k)(I_j - \mu_k) \right)
\end{aligned}$$

$$J(\alpha) = \sum_k \bar{\alpha}_k^T \bar{G}_k^T \bar{G}_k \bar{\alpha}_k$$



$$J(\alpha) = \alpha^T L \alpha$$

L is a large sparse N -by- N matrix whose (i, j) element is

$$\sum_{k|(i,j) \in w_k} \left(\delta_{ij} - \frac{1}{|w_k|} \left(1 + \frac{1}{\sigma_k^2 + \epsilon/|w_k|} (I_i - \mu_k)(I_j - \mu_k) \right) \right)$$

N is the number of pixels in the image

Color Images

color line model

$$\alpha_i \approx \sum_c a^c I_i^c + b \quad \text{sum over color channels}$$

$$F_i = \beta_i^F F_1 + (1 - \beta_i^F) F_2 \quad \leftarrow \text{linear mixture of two colors}$$

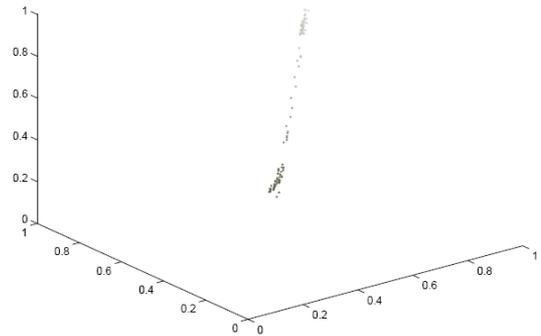
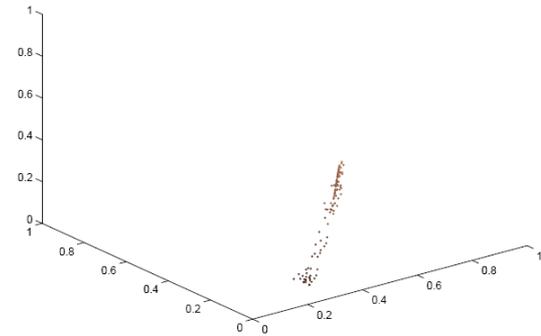
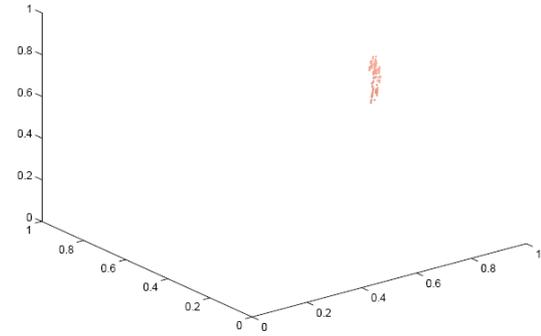
$$B_i = \beta_i^B B_1 + (1 - \beta_i^B) B_2$$

$$I_i^c = \alpha_i (\beta_i^F F_1^c + (1 - \beta_i^F) F_2^c) + (1 - \alpha_i) (\beta_i^B B_1^c + (1 - \beta_i^B) B_2^c)$$

$$H \begin{bmatrix} \alpha_i \\ \alpha_i \beta_i^F \\ (1 - \alpha_i) \beta_i^B \end{bmatrix} = I_i - B_2$$

$$J(\alpha) = \sum_k \bar{\alpha}_k^T \bar{G}_k^T \bar{G}_k \bar{\alpha}_k$$

Color Line Model





Alpha Matting of Color Images

$$J(\alpha, a, b) = \sum_{j \in I} \left(\sum_{i \in w_j} \left(\alpha_i - \sum_c a_j^c I_i^c - b_j \right)^2 + \epsilon \sum_c a_j^{c^2} \right)$$

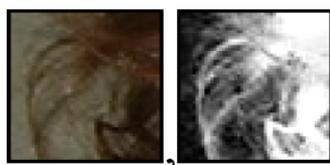
$$J(\alpha) = \alpha^T L \alpha$$

L is a large sparse N -by- N matrix whose (i, j) element is

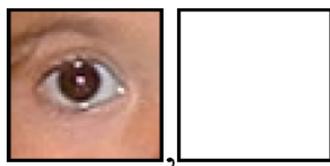
$$\sum_{k | (i, j) \in w_k} \left(\delta_{ij} - \frac{1}{|w_k|} \left(\mathbf{1} + (I_i - \mu_k)^T (\Sigma_k + \frac{\epsilon \mathbf{I}_3}{|w_k|})^{-1} (I_j - \mu_k) \right) \right)$$

where N is the number of pixels in the image, Σ_k is a 3-by-3 covariance matrix and μ_k a 3-by-1 mean vector of the colors in a window w_k , and \mathbf{I}_3 is the 3-by-3 identity matrix.

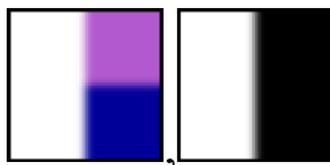
$$\alpha_i \approx \sum_c a^c I_i^c + b$$



$$\text{Grayscale Image} = 0 \cdot \text{Red Channel} - 2 \cdot \text{Green Channel} + 0 \cdot \text{Blue Channel} + 1$$



$$\text{White Square} = 0 \cdot \text{Red Channel} + 0 \cdot \text{Green Channel} + 0 \cdot \text{Blue Channel} + 1$$



$$\text{Black/White Bar} = -1 \cdot \text{Red Channel} + 2 \cdot \text{Green Channel} + 0 \cdot \text{Blue Channel} + 0$$



Constraints and User Interface

$$\alpha = \operatorname{argmin} \alpha^T L \alpha + \lambda (\alpha^T - b_S^T) D_S (\alpha - b_S)$$

vector of scribbles
0: background
1: foreground

diagonal matrix
1: constrained
pixels

solving the sparse linear system

$$(L + \lambda D_S) \alpha = \lambda b_S$$

Reconstructing F and B

$$\min \sum_{i \in I} \sum_c (\alpha_i F_i^c + (1 - \alpha_i) B_i^c - I_i^c)^2$$
$$+ |\alpha_{i_x}| \left((F_{i_x}^c)^2 + (B_{i_x}^c)^2 \right) + |\alpha_{i_y}| \left((F_{i_y}^c)^2 + (B_{i_y}^c)^2 \right)$$

x derivatives

- › Introducing some smoothness priors
- › The smoothness priors are stronger in the presence of matte edges